

# NAG C Library Function Document

## nag\_dtprfs (f07uhc)

### 1 Purpose

nag\_dtprfs (f07uhc) returns error bounds for the solution of a real triangular system of linear equations with multiple right-hand sides,  $AX = B$  or  $A^T X = B$ , using packed storage.

### 2 Specification

```
void nag_dtprfs (Nag_OrderType order, Nag_UptoType uplo, Nag_TransType trans,
                 Nag_DiagType diag, Integer n, Integer nrhs, const double ap[],
                 const double b[], Integer pdb, const double x[], Integer pdx, double ferr[],
                 double berr[], NagError *fail)
```

### 3 Description

nag\_dtprfs (f07uhc) returns the backward errors and estimated bounds on the forward errors for the solution of a real triangular system of linear equations with multiple right-hand sides  $AX = B$  or  $A^T X = B$ , using packed storage. The function handles each right-hand side vector (stored as a column of the matrix  $B$ ) independently, so we describe the function of nag\_dtprfs (f07uhc) in terms of a single right-hand side  $b$  and solution  $x$ .

Given a computed solution  $x$ , the function computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of  $A$  and  $b$  such that  $x$  is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where  $\hat{x}$  is the true solution.

For details of the method, see the f07 Chapter Introduction.

### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Parameters

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **uplo** – Nag\_UptoType *Input*

*On entry:* indicates whether  $A$  is upper or lower triangular as follows:

if **uplo** = **Nag\_Upper**,  $A$  is upper triangular;  
 if **uplo** = **Nag\_Lower**,  $A$  is lower triangular.

*Constraint:* **uplo** = **Nag\_Upper** or **Nag\_Lower**.

3: **trans** – Nag\_TransType *Input*

*On entry:* indicates the form of the equations as follows:

if **trans** = **Nag\_NoTrans**, the equations are of the form  $AX = B$ ;

if **trans** = **Nag\_Trans** or **Nag\_ConjTrans**, the equations are of the form  $A^T X = B$ .

*Constraint:* **trans** = **Nag\_NoTrans**, **Nag\_Trans** or **Nag\_ConjTrans**.

4: **diag** – Nag\_DiagType *Input*

*On entry:* indicates whether  $A$  is a non-unit or unit triangular matrix as follows:

if **diag** = **Nag\_NonUnitDiag**,  $A$  is a non-unit triangular matrix;

if **diag** = **Nag\_UnitDiag**,  $A$  is a unit triangular matrix; the diagonal elements are not referenced and are assumed to be 1.

*Constraint:* **diag** = **Nag\_NonUnitDiag** or **Nag\_UnitDiag**.

5: **n** – Integer *Input*

*On entry:*  $n$ , the order of the matrix  $A$ .

*Constraint:* **n**  $\geq 0$ .

6: **nrhs** – Integer *Input*

*On entry:*  $r$ , the number of right-hand sides.

*Constraint:* **nrhs**  $\geq 0$ .

7: **ap**[*dim*] – const double *Input*

**Note:** the dimension, *dim*, of the array **ap** must be at least  $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ .

*On entry:* the  $n$  by  $n$  triangular matrix  $A$ , packed by rows or columns. The storage of elements  $a_{ij}$  depends on the **order** and **uplo** parameters as follows:

if **order** = **Nag\_ColMajor** and **uplo** = **Nag\_Upper**,  
 $a_{ij}$  is stored in **ap**[( $j - 1$ )  $\times$   $j/2 + i - 1$ ], for  $i \leq j$ ;

if **order** = **Nag\_ColMajor** and **uplo** = **Nag\_Lower**,  
 $a_{ij}$  is stored in **ap**[( $2n - j$ )  $\times$  ( $j - 1$ )/2 +  $i - 1$ ], for  $i \geq j$ ;

if **order** = **Nag\_RowMajor** and **uplo** = **Nag\_Upper**,  
 $a_{ij}$  is stored in **ap**[( $2n - i$ )  $\times$  ( $i - 1$ )/2 +  $j - 1$ ], for  $i \leq j$ ;

if **order** = **Nag\_RowMajor** and **uplo** = **Nag\_Lower**,  
 $a_{ij}$  is stored in **ap**[( $i - 1$ )  $\times$   $i/2 + j - 1$ ], for  $i \geq j$ .

8: **b**[*dim*] – const double *Input*

**Note:** the dimension, *dim*, of the array **b** must be at least  $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$  when **order** = **Nag\_ColMajor** and at least  $\max(1, \mathbf{pdb} \times \mathbf{n})$  when **order** = **Nag\_RowMajor**.

If **order** = **Nag\_ColMajor**, the  $(i, j)$ th element of the matrix  $B$  is stored in **b**[( $j - 1$ )  $\times$  **pdb** +  $i - 1$ ] and if **order** = **Nag\_RowMajor**, the  $(i, j)$ th element of the matrix  $B$  is stored in **b**[( $i - 1$ )  $\times$  **pdb** +  $j - 1$ ].

*On entry:* the  $n$  by  $r$  right-hand side matrix  $B$ .

- 9: **pdb** – Integer *Input*  
*On entry:* the stride separating matrix row or column elements (depending on the value of **order**) in the array **b**.  
*Constraints:*  
 if **order** = Nag\_ColMajor, **pdb**  $\geq \max(1, \mathbf{n})$ ;  
 if **order** = Nag\_RowMajor, **pdb**  $\geq \max(1, \mathbf{nrhs})$ .
- 10: **x**[*dim*] – const double *Input*  
**Note:** the dimension, *dim*, of the array **x** must be at least  $\max(1, \mathbf{pdx} \times \mathbf{nrhs})$  when **order** = Nag\_ColMajor and at least  $\max(1, \mathbf{pdx} \times \mathbf{n})$  when **order** = Nag\_RowMajor.  
 If **order** = Nag\_ColMajor, the  $(i, j)$ th element of the matrix  $X$  is stored in **x**[(*j* – 1)  $\times$  **pdx** + *i* – 1] and if **order** = Nag\_RowMajor, the  $(i, j)$ th element of the matrix  $X$  is stored in **x**[(*i* – 1)  $\times$  **pdx** + *j* – 1].  
*On entry:* the *n* by *r* solution matrix  $X$ , as returned by nag\_dptrs (f07uec).
- 11: **pdx** – Integer *Input*  
*On entry:* the stride separating matrix row or column elements (depending on the value of **order**) in the array **x**.  
*Constraints:*  
 if **order** = Nag\_ColMajor, **pdx**  $\geq \max(1, \mathbf{n})$ ;  
 if **order** = Nag\_RowMajor, **pdx**  $\geq \max(1, \mathbf{nrhs})$ .
- 12: **ferr**[*dim*] – double *Output*  
**Note:** the dimension, *dim*, of the array **ferr** must be at least  $\max(1, \mathbf{nrhs})$ .  
*On exit:* **ferr**[*j* – 1] contains an estimated error bound for the *j*th solution vector, that is, the *j*th column of  $X$ , for  $j = 1, 2, \dots, r$ .
- 13: **berr**[*dim*] – double *Output*  
**Note:** the dimension, *dim*, of the array **berr** must be at least  $\max(1, \mathbf{nrhs})$ .  
*On exit:* **berr**[*j* – 1] contains the component-wise backward error bound  $\beta$  for the *j*th solution vector, that is, the *j*th column of  $X$ , for  $j = 1, 2, \dots, r$ .
- 14: **fail** – NagError \* *Output*  
 The NAG error parameter (see the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_INT

On entry, **n** =  $\langle \text{value} \rangle$ .  
 Constraint: **n**  $\geq 0$ .

On entry, **nrhs** =  $\langle \text{value} \rangle$ .  
 Constraint: **nrhs**  $\geq 0$ .

On entry, **pdb** =  $\langle \text{value} \rangle$ .  
 Constraint: **pdb**  $> 0$ .

On entry, **pdx** =  $\langle \text{value} \rangle$ .  
 Constraint: **pdx**  $> 0$ .

### NE\_INT\_2

On entry, **pdb** =  $\langle \text{value} \rangle$ , **n** =  $\langle \text{value} \rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$ , **nrhs** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \text{nrhs})$ .

On entry, **pdx** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ .  
 Constraint: **pdx**  $\geq \max(1, \text{n})$ .

On entry, **pdx** =  $\langle value \rangle$ , **nrhs** =  $\langle value \rangle$ .  
 Constraint: **pdx**  $\geq \max(1, \text{nrhs})$ .

## NE\_ALLOC\_FAIL

Memory allocation failed.

## NE\_BAD\_PARAM

On entry, parameter  $\langle value \rangle$  had an illegal value.

## NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

## 7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

## 8 Further Comments

A call to nag\_dtprfs (f07uhc) involves, for each right-hand side, solving a number of systems of linear equations of the form  $Ax = b$  or  $A^T x = b$ ; the number is usually 4 or 5 and never more than 11. Each solution involves approximately  $n^2$  floating-point operations.

The complex analogue of this function is nag\_ztprfs (f07uvc).

## 9 Example

To solve the system of equations  $AX = B$  and to compute forward and backward error bounds, where

$$A = \begin{pmatrix} 4.30 & 0.00 & 0.00 & 0.00 \\ -3.96 & -4.87 & 0.00 & 0.00 \\ 0.40 & 0.31 & -8.02 & 0.00 \\ -0.27 & 0.07 & -5.95 & 0.12 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} -12.90 & -21.50 \\ 16.75 & 14.93 \\ -17.55 & 6.33 \\ -11.04 & 8.09 \end{pmatrix},$$

using packed storage for  $A$ .

### 9.1 Program Text

```
/* nag_dtprfs (f07uhc) Example Program.
*
* Copyright 2001 Numerical Algorithms Group.
*
* Mark 7, 2001.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
```

```

/* Scalars */
Integer ap_len, i, j, n, nrhs, berr_len, ferr_len;
Integer pdb, pdx;
Integer exit_status=0;
Nag_UptoType uplo_enum;

NagError fail;
Nag_OrderType order;
/* Arrays */
char uplo[2];
double *ap=0, *b=0, *berr=0, *ferr=0, *x=0;

#ifndef NAG_COLUMN_MAJOR
#define A_UPPER(I,J) ap[J*(J-1)/2 + I - 1]
#define A_LOWER(I,J) ap[(2*n-J)*(J-1)/2 + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
#define X(I,J) x[(J-1)*pdx + I - 1]
    order = Nag_ColMajor;
#else
#define A_LOWER(I,J) ap[I*(I-1)/2 + J - 1]
#define A_UPPER(I,J) ap[(2*n-I)*(I-1)/2 + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
#define X(I,J) x[(I-1)*pdx + J - 1]
    order = Nag_RowMajor;
#endif

INIT_FAIL(fail);
Vprintf("f07uhc Example Program Results\n\n");

/* Skip heading in data file */
Vscanf("%*[^\n] ");
Vscanf("%ld%ld%*[^\n] ", &n, &nrhs);
berr_len = nrhs;
ferr_len = nrhs;
ap_len = n*(n+1)/2;
#ifndef NAG_COLUMN_MAJOR
    pdb = n;
    pdx = n;
#else
    pdb = nrhs;
    pdx = nrhs;
#endif

/* Allocate memory */
if ( !(ap = NAG_ALLOC(ap_len, double)) ||
    !(b = NAG_ALLOC(n * nrhs, double)) ||
    !(berr = NAG_ALLOC(berr_len, double)) ||
    !(ferr = NAG_ALLOC(ferr_len, double)) ||
    !(x = NAG_ALLOC(n * nrhs, double)) )
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Read A and B from data file, and copy B to X */
Vscanf(' ', %ls '%*[^\n] ', uplo);
if (*(unsigned char *)uplo == 'L')
    uplo_enum = Nag_Lower;
else if (*(unsigned char *)uplo == 'U')
    uplo_enum = Nag_Upper;
else
{
    Vprintf("Unrecognised character for Nag_UptoType type\n");
    exit_status = -1;
    goto END;
}
if (uplo_enum == Nag_Upper)
{
    for (i = 1; i <= n; ++i)
    {

```

```

        for (j = i; j <= n; ++j)
            Vscanf("%lf", &A_UPPER(i,j));
    }
    Vscanf("%*[^\n] ");
}
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
            Vscanf("%lf", &A_LOWER(i,j));
    }
    Vscanf("%*[^\n] ");
}
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
        Vscanf("%lf", &B(i,j));
}
Vscanf("%*[^\n] ");
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
        X(i,j) = B(i,j);
}
/* Compute solution in the array X */
f07uec(order, uplo_enum, Nag_NoTrans, Nag_NonUnitDiag, n,
       nrhs, ap, x, pdx, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07uec.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Compute backward errors and estimated bounds on the */
/* forward errors */

f07uhc(order, uplo_enum, Nag_NoTrans, Nag_NonUnitDiag, n,
       nrhs, ap, b, pdb, x, pdx, ferr, berr, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07uhc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print solution */

Vprintf("\n");
x04cac(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs,
        x, pdx, "Solution(s)", 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04cac.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
Vprintf("\nBackward errors (machine-dependent)\n");

for (j = 1; j <= nrhs; ++j)
    Vprintf("%11.1e%s", berr[j-1], j%7==0 ?"\n":" ");
Vprintf("\nEstimated forward error bounds "
       "(machine-dependent)\n");
for (j = 1; j <= nrhs; ++j)
    Vprintf("%11.1e%s", ferr[j-1], (j%7==0||j==nrhs) ?"\n":" ");
END:
    if (ap) NAG_FREE(ap);
    if (b) NAG_FREE(b);
    if (berr) NAG_FREE(berr);
    if (ferr) NAG_FREE(ferr);

```

```

if (x) NAG_FREE(x);

return exit_status;
}

```

## 9.2 Program Data

```

f07uhc Example Program Data
 4 2 :Values of N and NRHS
 'L' :Value of UPLO
 4.30
-3.96 -4.87
 0.40  0.31 -8.02
-0.27  0.07 -5.95  0.12 :End of matrix A
-12.90 -21.50
 16.75  14.93
-17.55  6.33
-11.04  8.09          :End of matrix B

```

## 9.3 Program Results

f07uhc Example Program Results

```

Solution(s)
      1          2
1     -3.0000    -5.0000
2     -1.0000     1.0000
3      2.0000    -1.0000
4      1.0000     6.0000

```

Backward errors (machine-dependent)

  6.9e-17   0.0e+00

Estimated forward error bounds (machine-dependent)

  8.3e-14   2.6e-14

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